

## 6. The Positivstellensatz

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- Semialgebraic sets
- Tarski-Seidenberg and quantifier elimination
- Feasibility of semialgebraic sets
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- The real Nullstellensatz
- The Positivstellensatz
- Example: Farkas lemma
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## Basic Semialgebraic Sets

The *basic (closed) semialgebraic set* defined by polynomials  $f_1, \dots, f_m$  is

$$\left\{ x \in \mathbb{R}^n \mid f_i(x) \geq 0 \text{ for all } i = 1, \dots, m \right\}$$

## Examples

- The nonnegative orthant in  $\mathbb{R}^n$
- The cone of positive semidefinite matrices
- Feasible set of an SDP; polyhedra and spectrahedra

## Properties

- If  $S_1, S_2$  are basic closed semialgebraic sets, then so is  $S_1 \cap S_2$ ; i.e., the class is closed under intersection
- Not closed under union or projection

## Semialgebraic Sets

Given the basic semialgebraic sets, we may generate other sets by set theoretic operations; unions, intersections and complements.

A set generated by a finite sequence of these operations on basic semialgebraic sets is called a *semialgebraic set*.

Some examples:

- The set

$$S = \left\{ x \in \mathbb{R}^n \mid f(x) * 0 \right\}$$

is semialgebraic, where  $*$  denotes  $<, \leq, =, \neq$ .

- In particular every real variety is semialgebraic.
- We can also generate the semialgebraic sets via Boolean logical operations applied to polynomial equations and inequalities

## Semialgebraic Sets

Every semialgebraic set may be represented as either

- an intersection of unions

$$S = \bigcap_{i=1}^m \bigcup_{j=1}^{p_i} \left\{ x \in \mathbb{R}^n \mid \mathbf{sign} f_{ij}(x) = a_{ij} \right\} \text{ where } a_{ij} \in \{-1, 0, 1\}$$

- a finite union of sets of the form

$$\left\{ x \in \mathbb{R}^n \mid f_i(x) > 0, h_j(x) = 0 \text{ for all } i = 1, \dots, m, j = 1, \dots, p \right\}$$

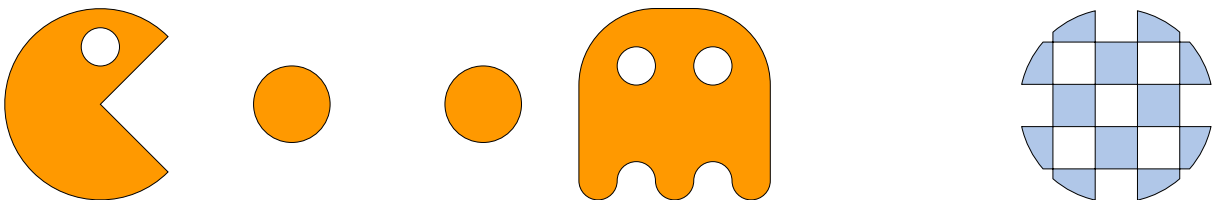
- in  $\mathbb{R}$ , a finite union of points and open intervals

Every *closed* semialgebraic set is a finite union of basic closed semialgebraic sets; i.e., sets of the form

$$\left\{ x \in \mathbb{R}^n \mid f_i(x) \geq 0 \text{ for all } i = 1, \dots, m \right\}$$

## Properties of Semialgebraic Sets

- If  $S_1, S_2$  are semialgebraic, so is  $S_1 \cup S_2$  and  $S_1 \cap S_2$
- The projection of a semialgebraic set is semialgebraic
- The closure and interior of a semialgebraic sets are both semialgebraic

- Some examples:
 

## Sets that are not Semialgebraic

Some sets are not semialgebraic; for example

- the graph  $\{ (x, y) \in \mathbb{R}^2 \mid y = e^x \}$
- the infinite staircase  $\{ (x, y) \in \mathbb{R}^2 \mid y = \lfloor x \rfloor \}$
- the infinite grid  $\mathbb{Z}^n$

## Tarski-Seidenberg and Quantifier Elimination

Tarski-Seidenberg theorem: if  $S \subset \mathbb{R}^{n+p}$  is semialgebraic, then so are

- $\{ x \in \mathbb{R}^n \mid \exists y \in \mathbb{R}^p (x, y) \in S \}$  (closure under projection)
- $\{ x \in \mathbb{R}^n \mid \forall y \in \mathbb{R}^p (x, y) \in S \}$  (complements and projections)

i.e., quantifiers do not add any expressive power

*Cylindrical algebraic decomposition* (CAD) may be used to compute the semialgebraic set resulting from quantifier elimination

## Feasibility of Semialgebraic Sets

Suppose  $S$  is a semialgebraic set; we'd like to solve the feasibility problem

Is  $S$  non-empty?

More specifically, suppose we have a semialgebraic set represented by polynomial inequalities and equations

$$S = \left\{ x \in \mathbb{R}^n \mid f_i(x) \geq 0, h_j(x) = 0 \text{ for all } i = 1, \dots, m, j = 1, \dots, p \right\}$$

- Important, non-trivial result: the feasibility problem is *decidable*.
- But NP-hard (even for a single polynomial, as we have seen)
- We would like to *certify* infeasibility

## Certificates So Far

- *The Nullstellensatz*: a necessary and sufficient condition for feasibility of *complex* varieties

$$\left\{ x \in \mathbb{C}^n \mid h_i(x) = 0 \forall i \right\} = \emptyset \iff -1 \in \mathbf{ideal}\{h_1, \dots, h_m\}$$

- *Valid inequalities*: a *sufficient* condition for infeasibility of *real basic* semialgebraic sets

$$\left\{ x \in \mathbb{R}^n \mid f_i(x) \geq 0 \forall i \right\} = \emptyset \iff -1 \in \mathbf{cone}\{f_1, \dots, f_m\}$$

- *Linear Programming*: necessary and sufficient conditions via duality for *real linear* equations and inequalities



## Certificates So Far

Degree \ Field	Complex	Real
Linear	<i>Range/Kernel</i> Linear Algebra	<i>Farkas Lemma</i> Linear Programming
Polynomial	<i>Nullstellensatz</i> Bounded degree: LP Groebner bases	???? ????

We'd like a method to construct certificates for

- *polynomial* equations
- over the *real* field

## Real Fields and Inequalities

If we can test feasibility of *real* equations then we can also test feasibility of real *inequalities* and *inequations*, because

- *inequalities*: there exists  $x \in \mathbb{R}$  such that  $f(x) \geq 0$  if and only if  
there exists  $(x, y) \in \mathbb{R}^2$  such that  $f(x) = y^2$
- *strict inequalities*: there exists  $x$  such that  $f(x) > 0$  if and only if  
there exists  $(x, y) \in \mathbb{R}^2$  such that  $y^2 f(x) = 1$
- *inequations*: there exists  $x$  such that  $f(x) \neq 0$  if and only if  
there exists  $(x, y) \in \mathbb{R}^2$  such that  $y f(x) = 1$

The underlying theory for real polynomials called *real algebraic geometry*

## Real Varieties

The *real variety* defined by polynomials  $h_1, \dots, h_m \in \mathbb{R}[x_1, \dots, x_n]$  is

$$\mathcal{V}_{\mathbb{R}}\{h_1, \dots, h_m\} = \{x \in \mathbb{R}^n \mid h_i(x) = 0 \text{ for all } i = 1, \dots, m\}$$

We'd like to solve the feasibility problem; is  $\mathcal{V}_{\mathbb{R}}\{h_1, \dots, h_m\} \neq \emptyset$ ?

We know

- Every polynomial in  $\mathbf{ideal}\{h_1, \dots, h_m\}$  vanishes on the feasible set.
- The (complex) Nullstellensatz:

$$-1 \in \mathbf{ideal}\{h_1, \dots, h_m\} \implies \mathcal{V}_{\mathbb{R}}\{h_1, \dots, h_m\} = \emptyset$$

- But this condition is not necessary over the reals

## The Real Nullstellensatz

Recall  $\Sigma$  is the cone of polynomials representable as *sums of squares*.

Suppose  $h_1, \dots, h_m \in \mathbb{R}[x_1, \dots, x_n]$ .

$$-1 \in \Sigma + \mathbf{ideal}\{h_1, \dots, h_m\} \iff \mathcal{V}_{\mathbb{R}}\{h_1, \dots, h_m\} = \emptyset$$

Equivalently, there is no  $x \in \mathbb{R}^n$  such that

$$h_i(x) = 0 \quad \text{for all } i = 1, \dots, m$$

if and only if there exists  $t_1, \dots, t_m \in \mathbb{R}[x_1, \dots, x_n]$  and  $s \in \Sigma$  such that

$$-1 = s + t_1 h_1 + \dots + t_m h_m$$

## Example

Suppose  $h(x) = x^2 + 1$ . Then clearly  $\mathcal{V}_{\mathbb{R}}\{h\} = \emptyset$

We saw earlier that the complex Nullstellensatz cannot be used to prove emptiness of  $\mathcal{V}_{\mathbb{R}}\{h\}$

But we have

$$-1 = s + th$$

with

$$s(x) = x^2 \quad \text{and} \quad t(x) = -1$$

and so the real Nullstellensatz implies  $\mathcal{V}_{\mathbb{R}}\{h\} = \emptyset$ .

The polynomial equation  $-1 = s + th$  gives a certificate of infeasibility.

## The Positivstellensatz

We now turn to feasibility for *basic semialgebraic sets*, with primal problem

Does there exist  $x \in \mathbb{R}^n$  such that

$$f_i(x) \geq 0 \quad \text{for all } i = 1, \dots, m$$

$$h_j(x) = 0 \quad \text{for all } j = 1, \dots, p$$

Call the feasible set  $S$ ; recall

- every polynomial in  $\mathbf{cone}\{f_1, \dots, f_m\}$  is nonnegative on  $S$
- every polynomial in  $\mathbf{ideal}\{h_1, \dots, h_p\}$  is zero on  $S$

The *Positivstellensatz* (Stengle 1974)

$$S = \emptyset \quad \iff \quad -1 \in \mathbf{cone}\{f_1, \dots, f_m\} + \mathbf{ideal}\{h_1, \dots, h_m\}$$

## Example

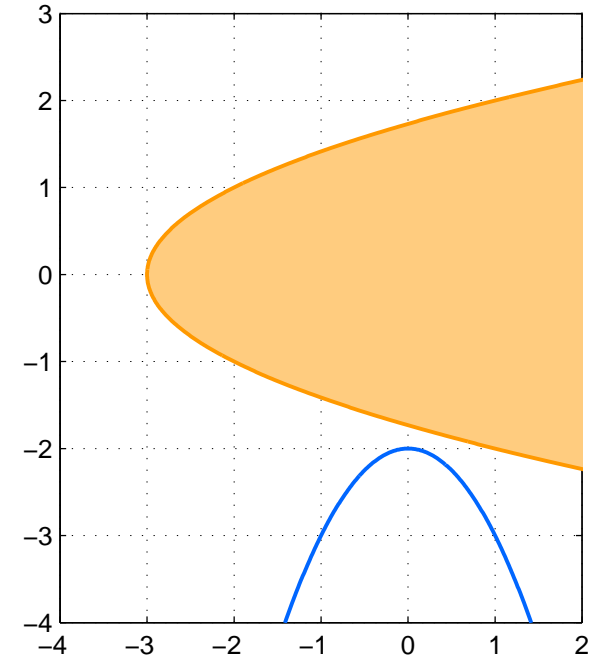
Consider the feasibility problem

$$S = \{ (x, y) \in \mathbb{R}^2 \mid f(x, y) \geq 0, h(x, y) = 0 \}$$

where

$$f(x, y) = x - y^2 + 3$$

$$h(x, y) = y + x^2 + 2$$



By the P-satz, the primal is infeasible if and only if there exist polynomials  $s_1, s_2 \in \Sigma$  and  $t \in \mathbb{R}[x, y]$  such that

$$-1 = s_1 + s_2 f + t h$$

A certificate is given by

$$s_1 = \frac{1}{3} + 2\left(y + \frac{3}{2}\right)^2 + 6\left(x - \frac{1}{6}\right)^2, \quad s_2 = 2, \quad t = -6.$$

## Explicit Formulation of the Positivstellensatz

The primal problem is

Does there exist  $x \in \mathbb{R}^n$  such that

$$f_i(x) \geq 0 \quad \text{for all } i = 1, \dots, m$$

$$h_j(x) = 0 \quad \text{for all } j = 1, \dots, p$$

The dual problem is

Do there exist  $t_i \in \mathbb{R}[x_1, \dots, x_n]$  and  $s_i, r_{ij}, \dots \in \Sigma$  such that

$$-1 = \sum_i h_i t_i + s_0 + \sum_i s_i f_i + \sum_{i \neq j} r_{ij} f_i f_j + \dots$$

These are *strong alternatives*



## Testing the Positivstellensatz

Do there exist  $t_i \in \mathbb{R}[x_1, \dots, x_n]$  and  $s_i, r_{ij}, \dots \in \Sigma$  such that

$$-1 = \sum_i t_i h_i + s_0 + \sum_i s_i f_i + \sum_{i \neq j} r_{ij} f_i f_j + \dots$$

- This is a convex feasibility problem in  $t_i, s_i, r_{ij}, \dots$
- To solve it, we need to choose a subset of the cone to search; i.e., the maximum degree of the above polynomial; then the problem is a *semidefinite program*
- This gives a *hierarchy* of syntactically verifiable certificates
- The validity of a certificate may be easily checked; e.g., linear algebra, random sampling
- Unless NP=co-NP, the certificates cannot *always* be polynomially sized.

## Example: Farkas Lemma

The primal problem; does there exist  $x \in \mathbb{R}^n$  such that

$$Ax + b \geq 0 \quad Cx + d = 0$$

Let  $f_i(x) = a_i^T x + b_i$ ,  $h_i(x) = c_i^T x + d_i$ . Then this system is infeasible if and only if

$$-1 \in \mathbf{cone}\{f_1, \dots, f_m\} + \mathbf{ideal}\{h_1, \dots, h_p\}$$

Searching over *linear combinations*, the primal is infeasible if there exist  $\lambda \geq 0$  and  $\mu$  such that

$$\lambda^T (Ax + b) + \mu^T (Cx + d) = -1$$

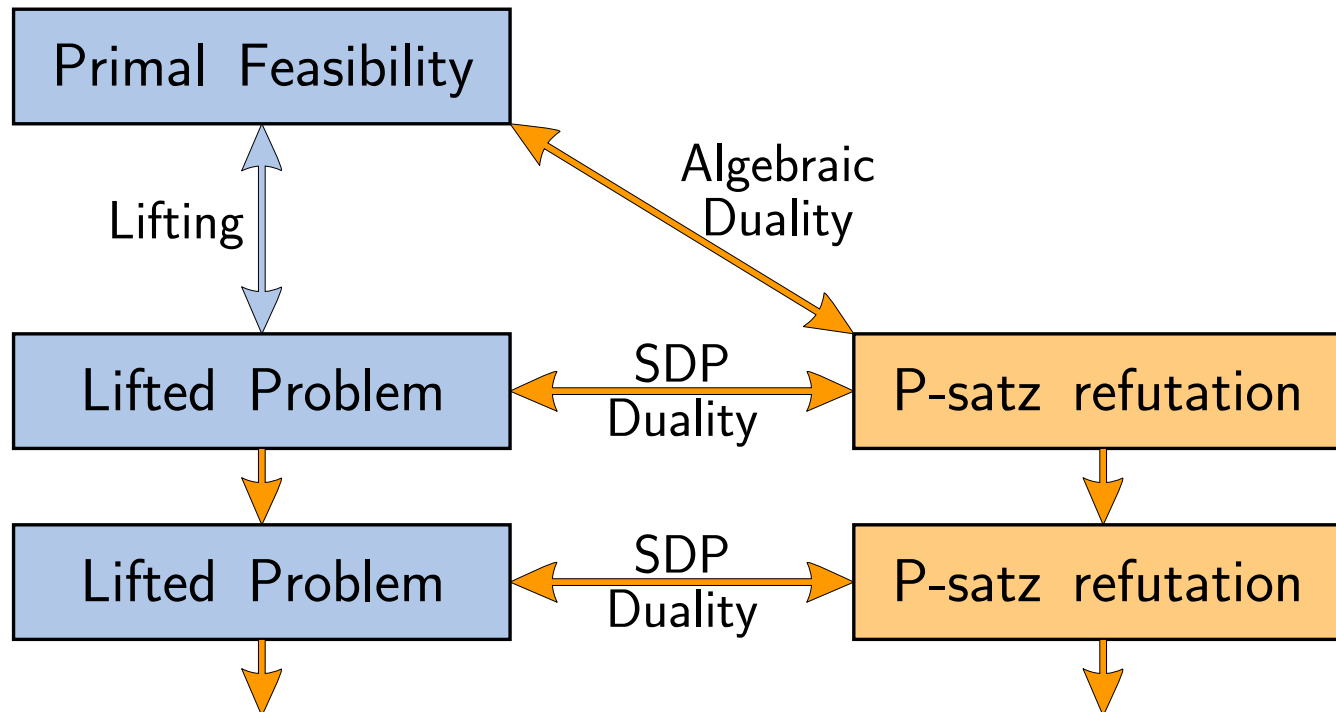
Equating coefficients, this is equivalent to

$$\lambda^T A + \mu^T C = 0 \quad \lambda^T b + \mu^T d = -1 \quad \lambda \geq 0$$

## Hierarchy of Certificates

- Interesting connections with logic, proof systems, etc.
- Failure to prove infeasibility (may) provide points in the set.
- Tons of applications:  
optimization, copositivity, dynamical systems, quantum mechanics...

## General Scheme



## Special Cases

Many known methods can be interpreted as fragments of P-satz refutations.

- LP duality: linear inequalities, constant multipliers.
- S-procedure: quadratic inequalities, constant multipliers
- Standard SDP relaxations for QP.
- The *linear representations* approach for functions  $f$  strictly positive on the set defined by  $f_i(x) \geq 0$ .

$$f(x) = s_0 + s_1 f_1 + \cdots + s_n f_n, \quad s_i \in \Sigma$$

## Converse Results

- *Losslessness*: when can we restrict *a priori* the class of certificates?
- Some cases are known; e.g., additional conditions such as linearity, perfect graphs, compactness, finite dimensionality, etc, can ensure specific *a priori* properties.

## Example: Boolean Minimization

$$x^T Q x \leq \gamma$$

$$x_i^2 - 1 = 0$$

A P-satz refutation holds if there is  $S \succeq 0$  and  $\lambda \in \mathbb{R}^n$ ,  $\varepsilon > 0$  such that

$$-\varepsilon = x^T S x + \gamma - x^T Q x + \sum_{i=1}^n \lambda_i (x_i^2 - 1)$$

which holds if and only if there exists a diagonal  $\Lambda$  such that  $Q \succeq \Lambda$ ,  $\gamma = \mathbf{trace} \Lambda - \varepsilon$ .

The corresponding optimization problem is

$$\begin{array}{ll} \text{maximize} & \mathbf{trace} \Lambda \\ \text{subject to} & Q \succeq \Lambda \\ & \Lambda \text{ is diagonal} \end{array}$$

## Example: S-Procedure

The primal problem; does there exist  $x \in \mathbb{R}^n$  such that

$$x^T F_1 x \geq 0$$

$$x^T F_2 x \geq 0$$

$$x^T x = 1$$

We have a P-satz refutation if there exists  $\lambda_1, \lambda_2 \geq 0$ ,  $\mu \in \mathbb{R}$  and  $S \succeq 0$  such that

$$-1 = x^T S x + \lambda_1 x^T F_1 x + \lambda_2 x^T F_2 x + \mu(1 - x^T x)$$

which holds if and only if there exist  $\lambda_1, \lambda_2 \geq 0$  such that

$$\lambda_1 F_1 + \lambda_2 F_2 \leq -I$$

Subject to an additional mild constraint qualification, this condition is also *necessary* for infeasibility.

## Exploiting Structure

What algebraic properties of the polynomial system yield efficient computation?

- *Sparseness*: few nonzero coefficients.
  - Newton polytopes techniques
  - Complexity does not depend on the degree
- *Symmetries*: invariance under a transformation group
  - Frequent in practice. Enabling factor in applications.
  - Can reflect underlying physical symmetries, or modelling choices.
  - SOS on *invariant rings*
  - Representation theory and invariant-theoretic techniques.
- *Ideal structure*: Equality constraints.
  - SOS on *quotient rings*
  - Compute in the coordinate ring. Quotient bases (Groebner)

## Example: Structured Singular Value

- Structured singular value  $\mu$  and related problems: provides better upper bounds.
- $\mu$  is a measure of robustness: how big can a structured perturbation be, without losing stability.
- A standard semidefinite relaxation: the  $\mu$  upper bound.
  - Morton and Doyle's counterexample with four scalar blocks.
  - Exact value: approx. 0.8723
  - Standard  $\mu$  upper bound: 1
  - New bound: 0.895



## Example: Matrix Copositivity

A matrix  $M \in \mathbb{R}^{n \times n}$  is *copositive* if

$$x^T M x \geq 0 \quad \forall x \in \mathbb{R}^n, x_i \geq 0.$$

- The set of copositive matrices is a convex closed cone, but...
- Checking copositivity is coNP-complete
- Very important in QP. Characterization of local solutions.
- The P-satz gives a family of computable SDP conditions, via:

$$(x^T x)^d (x^T M x) = s_0 + \sum_i s_i x_i + \sum_{jk} s_{jk} x_j x_k + \dots$$

## Example: Geometric Inequalities

**Ono's inequality:** For an acute triangle,

$$(4K)^6 \geq 27 \cdot (a^2 + b^2 - c^2)^2 \cdot (b^2 + c^2 - a^2)^2 \cdot (c^2 + a^2 - b^2)^2$$

where  $K$  and  $a, b, c$  are the area and lengths of the edges.

The inequality is true if:

$$\left. \begin{array}{l} t_1 := a^2 + b^2 - c^2 \geq 0 \\ t_2 := b^2 + c^2 - a^2 \geq 0 \\ t_3 := c^2 + a^2 - b^2 \geq 0 \end{array} \right\} \Rightarrow (4K)^6 \geq 27 \cdot t_1^2 \cdot t_2^2 \cdot t_3^2$$

A simple proof: define

$$s(x, y, z) = (x^4 + x^2y^2 - 2y^4 - 2x^2z^2 + y^2z^2 + z^4)^2 + 15 \cdot (x - z)^2(x + z)^2(z^2 + x^2 - y^2)^2.$$

We have then

$$(4K)^6 - 27 \cdot t_1^2 \cdot t_2^2 \cdot t_3^2 = s(a, b, c) \cdot t_1 \cdot t_2 + s(c, a, b) \cdot t_1 \cdot t_3 + s(b, c, a) \cdot t_2 \cdot t_3$$

therefore *proving* the inequality.